

Copy Right

- Allows possessor to give rights to another
- Often attached to a right, so only applies to that right
 - r is read right that cannot be copied
 - rc is read right that can be copied
- Is copy flag copied when giving r rights?
 - Depends on model, instantiation of model

Own Right

- Usually allows possessor to change entries in ACM column
 - So owner of object can add, delete rights for others
 - May depend on what system allows
 - Can't give rights to specific (set of) users
 - Can't pass copy flag to specific (set of) users

Attenuation of Privilege

- Principle says you can't give rights you do not possess
 - Restricts addition of rights within a system
 - Usually *ignored* for owner
 - Why? Owner gives herself rights, gives them to others, deletes her rights.

Foundational Results

- Overview
- Harrison-Ruzzo-Ullman result
 - Corollaries
- Take-Grant Protection Model
- SPM and successors

Overview

- Safety Question
- HRU Model
- Take-Grant Protection Model
- SPM, ESPM
 - Multiparent joint creation
- Expressive power
- Typed Access Matrix Model

What Is “Secure”?

- Adding a generic right r where there was not one is “leaking”
- If a system S , beginning in initial state s_0 , cannot leak right r , it is *safe with respect to the right r* .

Safety Question

- Does there exist an algorithm for determining whether a protection system S with initial state s_0 is safe with respect to a generic right r ?
 - Here, “safe” = “secure” for an abstract model

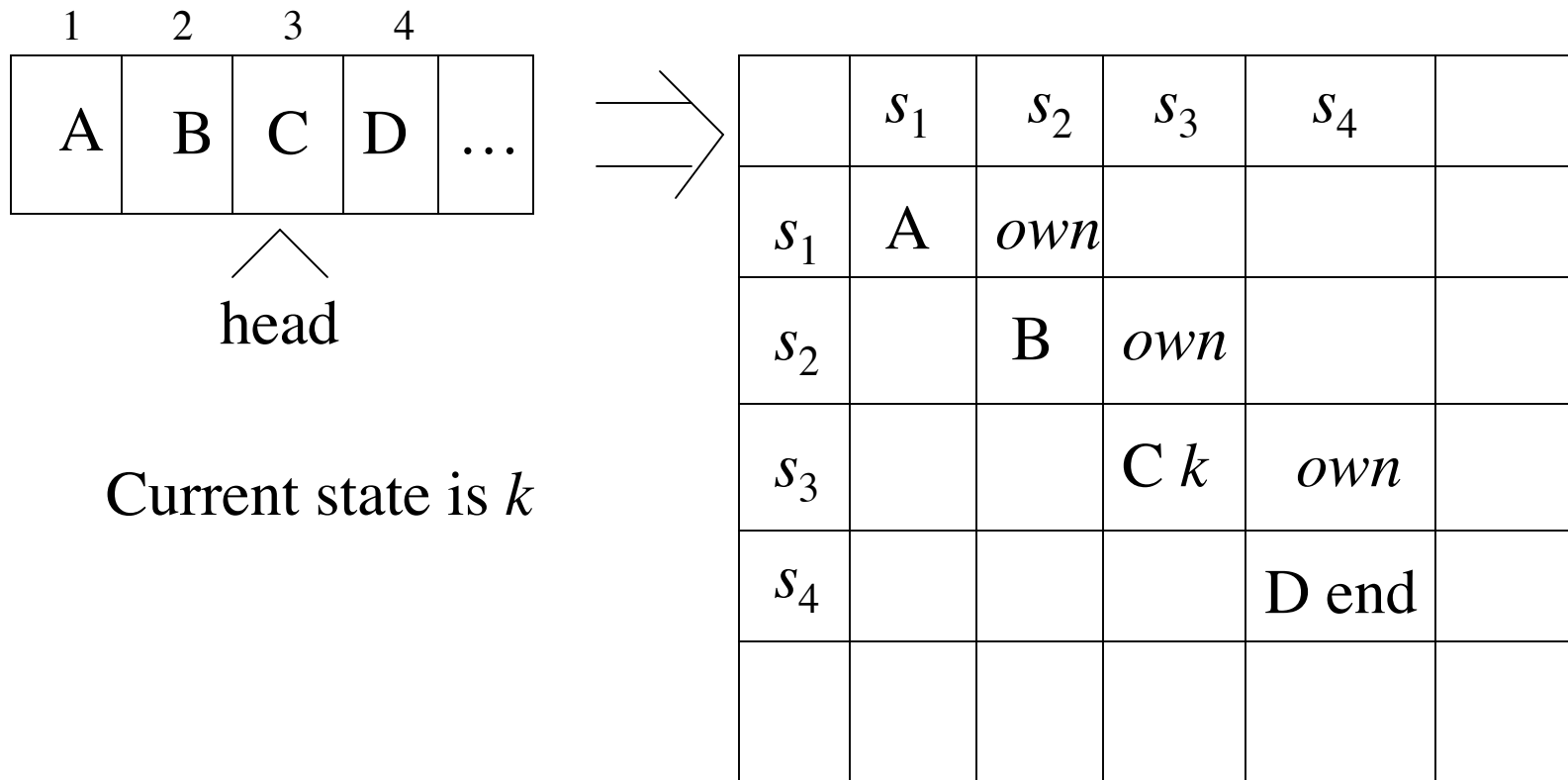
Mono-Operational Commands

- Answer: *yes*
 - Sketch of proof:
 - Consider minimal sequence of commands c_1, \dots, c_k to leak the right.
 - Can omit **delete**, **destroy**
 - Can merge all **creates** into one
- Worst case: insert every right into every entry; with s subjects and o objects initially, and n rights, upper bound is $k \leq n(s+1)(o+1)$

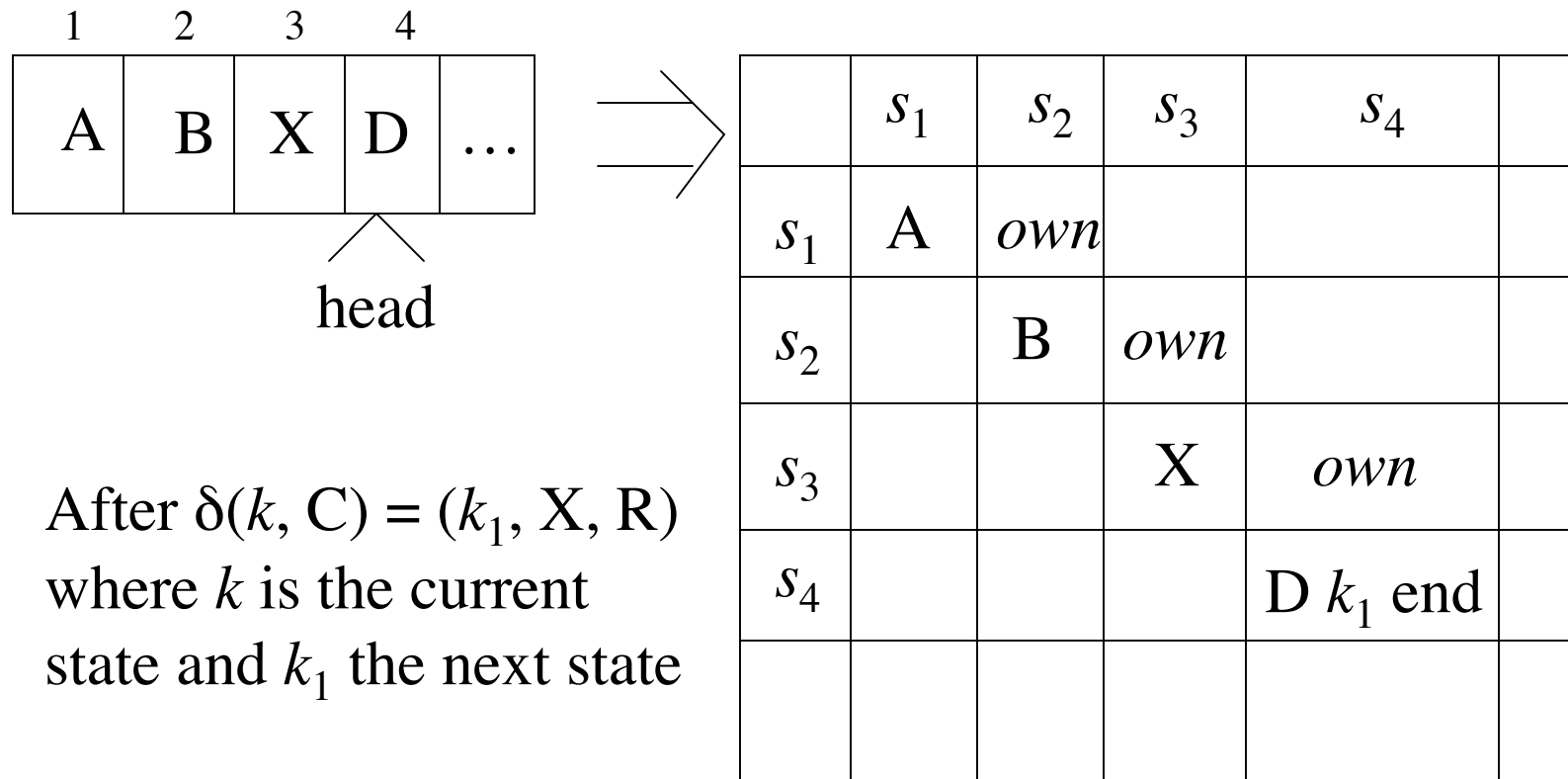
General Case

- Answer: *no*
- Sketch of proof:
 - Reduce halting problem to safety problem
 - Turing Machine review:
 - Infinite tape in one direction
 - States K , symbols M ; distinguished blank b
 - Transition function $\delta(k, m) = (k', m', L)$ means in state k , symbol m on tape location replaced by symbol m' , head moves to left one square, and enters state k'
 - Halting state is q_f ; TM halts when it enters this state

Mapping



Mapping



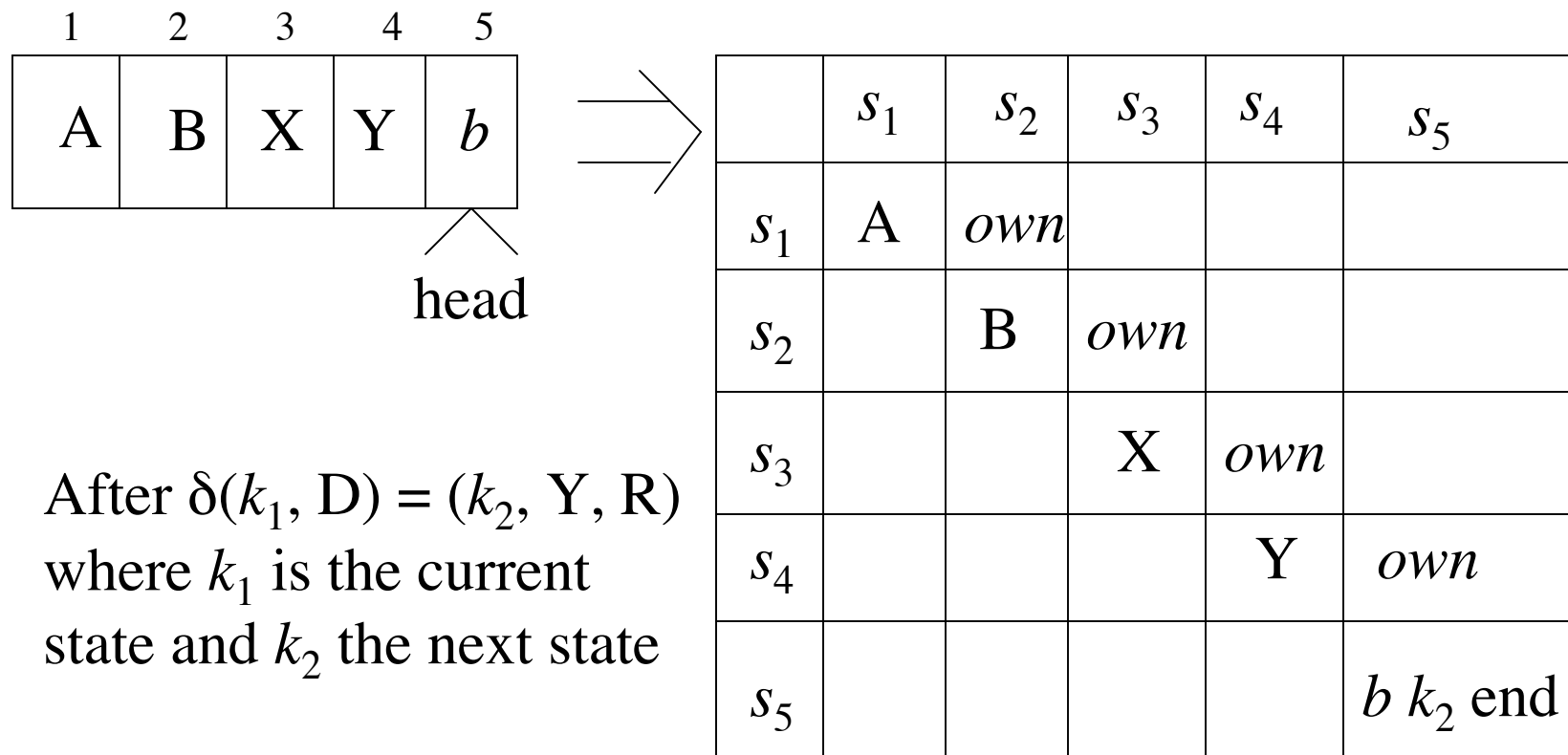
After $\delta(k, C) = (k_1, X, R)$
 where k is the current
 state and k_1 the next state

Command Mapping

$\delta(k, C) = (k_1, X, R)$ at intermediate becomes

```
command  $c_{k,c}(s_3, s_4)$   
if own in  $A[s_3, s_4]$  and  $k$  in  $A[s_3, s_3]$   
    and  $C$  in  $A[s_3, s_3]$   
then  
    delete  $k$  from  $A[s_3, s_3]$ ;  
    delete  $C$  from  $A[s_3, s_3]$ ;  
    enter  $X$  into  $A[s_3, s_3]$ ;  
    enter  $k_1$  into  $A[s_4, s_4]$ ;  
end
```

Mapping



After $\delta(k_1, D) = (k_2, Y, R)$
 where k_1 is the current
 state and k_2 the next state

Command Mapping

$\delta(k_1, D) = (k_2, Y, R)$ at end becomes

```
command crightmostk,c(s4, s5)  
if end in A[s4, s4] and k1 in A[s4, s4]  
    and D in A[s4, s4]  
then  
    delete end from A[s4, s4];  
    create subject s5;  
    enter own into A[s4, s5];  
    enter end into A[s5, s5];  
    delete k1 from A[s4, s4];  
    delete D from A[s4, s4];  
    enter Y into A[s4, s4];  
    enter k2 into A[s5, s5];  
end
```

Rest of Proof

- Protection system exactly simulates a TM
 - Exactly 1 *end* right in ACM
 - 1 right in entries corresponds to state
 - Thus, at most 1 applicable command
- If TM enters state q_f , then right has leaked
- If safety question decidable, then represent TM as above and determine if q_f leaks
 - Implies halting problem decidable
- Conclusion: safety question undecidable

Other Results

- Set of unsafe systems is recursively enumerable
- Delete **create** primitive; then safety question is complete in **P-SPACE**
- Delete **destroy**, **delete** primitives; then safety question is undecidable
 - Systems are monotonic
- Safety question for monoconditional, monotonic protection systems is decidable
- Safety question for monoconditional protection systems with **create**, **enter**, **delete** (and no **destroy**) is decidable.

Take-Grant Protection Model

- A specific (not generic) system
 - Set of rules for state transitions
- Safety decidable, and in time linear with the size of the system
- Goal: find conditions under which rights can be transferred from one entity to another in the system

System

- objects (files, ...)
- subjects (users, processes, ...)
- ⊗ don't care (either a subject or an object)

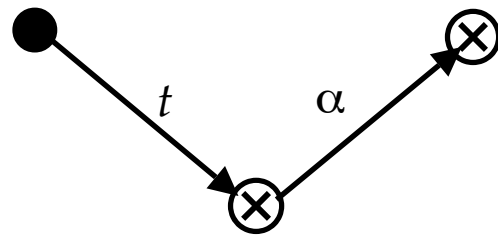
$G \mid\!-\!_x G'$ apply a rewriting rule x (witness) to
 G to get G'

$G \mid\!-\!^* G'$ apply a sequence of rewriting rules
 (witness) to G to get G'

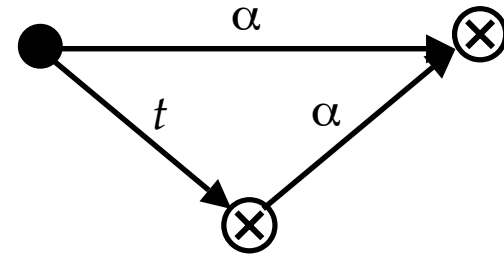
$R = \{ t, g, r, w, \dots \}$ set of rights

Rules

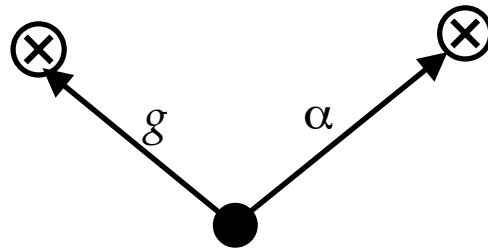
take



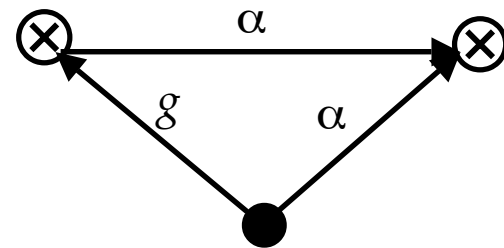
\vdash



grant



\vdash

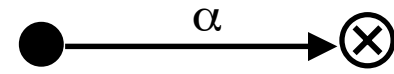


More Rules

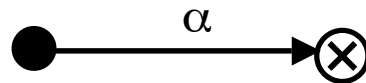
create



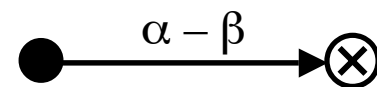
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remove

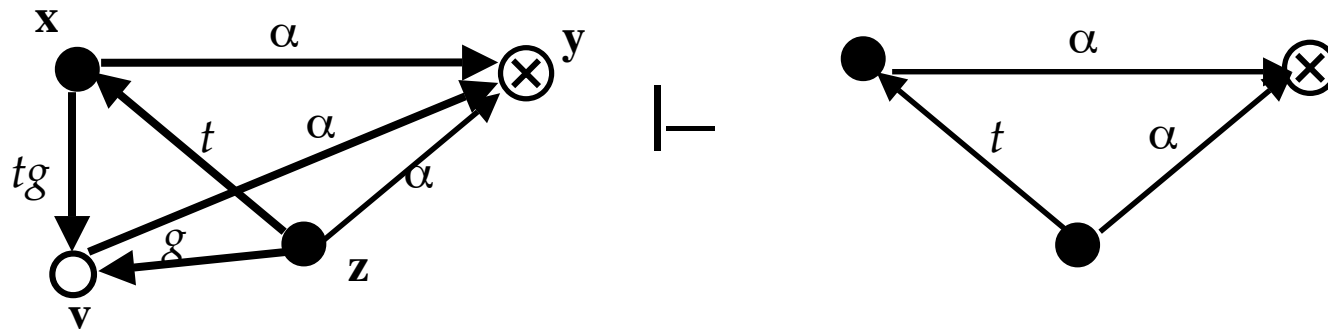


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These four rules are called the *de jure* rules

Symmetry



1. **x** creates (*tg* to new) **v**
2. **z** takes (*g* to **v**) from **x**
3. **z** grants (α to **y**) to **v**
4. **x** takes (α to **y**) from **v**

Similar result for grant

Islands

- *tg*-path: path of distinct vertices connected by edges labeled *t* or *g*
 - Call them “*tg*-connected”
- island: maximal *tg*-connected subject-only subgraph
 - Any right one vertex has can be shared with any other vertex

Initial, Terminal Spans

- *initial span* from \mathbf{x} to \mathbf{y}
 - \mathbf{x} subject
 - tg -path between \mathbf{x} , \mathbf{y} with word in $\{ \vec{t}^* \vec{g} \} \cup \{ \mathbf{v} \}$
 - Means \mathbf{x} can give rights it has to \mathbf{y}
- *terminal span* from \mathbf{x} to \mathbf{y}
 - \mathbf{x} subject
 - tg -path between \mathbf{x} , \mathbf{y} with word in $\{ \vec{t}^* \} \cup \{ \mathbf{v} \}$
 - Means \mathbf{x} can acquire any rights \mathbf{y} has