

Access Control Matrix Model

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- 1 Modeling
- 2 What is an ACM?
- 3 Some examples
 - Boolean expressions for database control
 - History for program execution control
- 4 Formal model
 - Primitive operations
 - Types of commands
- 5 Propagating rights
 - Copy and own
 - Attenuation of privilege
- 6 What Next?
- 7 Decidability of security
 - Mono-operational command case
 - General case

Models

- Abstract irrelevant details of entity or process being modeled
 - Allows you to focus on aspects that are of interest
 - *If done correctly*, results from analyzing the model apply to entity or process
- Assumption: nothing you omit affects the application of the results

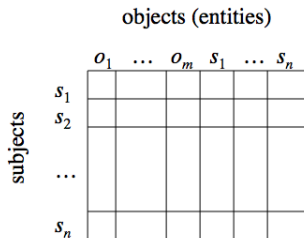
Protection State

Protection state of system describes current settings, values relevant to protection

- Access control matrix representation of protection state
 - Describes protection state precisely
 - Matrix describing rights of subjects (rows) over objects (columns)
 - State transitions change elements of matrix
- *Subject* is active entities (processes, users, etc.)
- *Object* has 2 meanings:
 - Passive entity (*not* a subject)
 - Any entity acting passively (so can be a subject)

Context tells you which sense is used

Description



- Subjects $S = \{s_1, \dots, s_n\}$
- Objects $O = \{o_1, \dots, o_m\}$
- Rights $R = \{r_1, \dots, r_k\}$
- Entries $A[s_i, o_j] \subseteq R$
- $A[s_i, o_j] = \{r_x, \dots, r_y\}$ means subject s_i has rights r_x, \dots, r_y over object o_j

Access Control Matrix for System

- Processes p, q
- Files f, g
- Rights r, w, x, a, o
 - Rights are merely symbols; interpretation depends on system
 - Example: on UNIX, r means “read” for file and “list” for directory

	f	g	p	q
p	rwo	r	$rwxo$	w
q	a	ro	r	$rwxo$

Access Control Matrix for Program

- Procedures *inc_ctr*, *dec_ctr*, *manage*
- Variable *counter*
- Rights +, -, x, *call*

	<i>counter</i>	<i>inc_ctr</i>	<i>dec_ctr</i>	<i>manage</i>
<i>inc_ctr</i>	+			
<i>dec_ctr</i>	-			
<i>manage</i>		<i>call</i>	<i>call</i>	<i>call</i>

Access Control Matrix for Database

- Access control matrix shows allowed access to database fields
 - *Subjects* have attributes
 - *Verbs* define type of access
 - *Rules* associated with objects, verb pair
- Subject attempts to access object
 - Rule for object, verb evaluated
 - Result controls granting, denying access



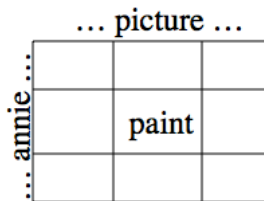
Boolean Expressions and Access

- Subject *annie*: attributes role (artist), groups (creative)
- Verb *paint*: default 0 (deny unless explicitly granted)
- Object *picture*: Rule is

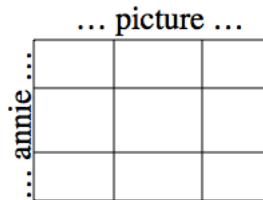
paint: 'artist' **in** *subject.role* **and**
 'creative' **in** *subject.groups* **and**
time.hour ≥ 0 **and** *time.hour* < 5

Example: ACM at 3 a.m. and 10 a.m.

At 3 a.m., time condition met;
ACM is:



At 10 a.m., time condition not met;
ACM is



Executing Downloaded Programs

- Downloaded programs may access system in unauthorized ways
 - Example: Download Trojan horse that modifies configuration, control files
- Condition access rights upon the rights of previously executed code (*i.e.*, history)
 - Each piece of code has *set of static rights*
 - Executing process has *set of current rights*
 - When piece of code runs, its rights are $\text{set of current rights} \cap \text{set of static rights}$



Example Programs

main runs, loads *helper_proc* and runs it

```
// This routine has no filesystem access rights
```

```
// beyond those in a limited, temporary area
```

```
procedure helper_proc()
```

```
    return sys_kernel_file;
```

```
// But this has the right to delete files
```

```
program main()
```

```
    sys_load_file(helper_proc);
```

```
    file = helper_proc();
```

```
    sys_delete_file(file);
```

sys_kernel_file is system kernel

tmp_file file in limited, temporary area *helper_proc* can access

Accesses

- Initial static rights:

	<i>sys_kernel_file</i>	<i>tmp_file</i>
<i>main</i>	delete	delete
<i>helper_proc</i>		delete

- Program starts; its rights are those of *main*:

	<i>sys_kernel_file</i>	<i>tmp_file</i>
<i>main</i>	delete	delete
<i>helper_proc</i>		delete
<i>process</i>	delete	delete

- After *helper_proc* called, process loses right to delete kernel:

	<i>sys_kernel_file</i>	<i>tmp_file</i>
<i>main</i>	delete	delete
<i>helper_proc</i>		delete
<i>process</i>		delete

State Transitions

- Represent changes to the protection state of the system
- \vdash represents transition
 - $X_i \vdash_{\tau} X_{i+1}$: command τ moves system from state X_i to state X_{i+1}
 - $X_i \vdash^* X_{i+1}$: a sequence of commands moves system from state X_i to state X_{i+1}
- Commands sometimes called *transformation procedures*

Primitive Operations

- **create subject s ; create object o**
 - Creates new row, column in ACM; creates new column in ACM
- **destroy subject s ; destroy object o**
 - Deletes row, column from ACM; deletes column from ACM
- **enter r into $A[s, o]$**
 - Adds r rights for subject s over object o
- **delete r from $A[s, o]$**
 - Removes r rights from subject s over object o

create subject

- Precondition: $s \notin S$
- Primitive command: **create subject** s
- Postconditions:
 - $S' = S \cup \{s\}, O' = O \cup \{s\}$
 - $(\forall y \in O')[A'[s, y] = \emptyset], (\forall x \in S')[A'[x, s] = \emptyset]$
 - $(\forall x \in S)(\forall y \in O)[A'[x, y] = A[x, y]]$

create object

- Precondition: $o \notin O$
- Primitive command: **create object** o
- Postconditions:
 - $S' = S, O' = O \cup \{o\}$
 - $(\forall x \in S')[A'[x, o] = \emptyset]$
 - $(\forall x \in S)(\forall y \in O)[A'[x, y] = A[x, y]]$

enter

- Precondition: $s \in S, o \in O$
- Primitive command: **enter** r **into** $A[s, o]$
- Postconditions:
 - $S' = S, O' = O$
 - $A'[s, o] = A[s, o] \cup \{r\}$
 - $(\forall x \in S)(\forall y \in O' - \{o\})[A'[x, y] = A[x, y]]$
 - $(\forall x \in S - \{s\})(\forall y \in O')[A'[x, y] = A[x, y]]$

delete

- Precondition: $s \in S, o \in O$
- Primitive command: **delete** r **from** $A[s, o]$
- Postconditions:
 - $S' = S, O' = O$
 - $A'[s, o] = A[s, o] - \{r\}$
 - $(\forall x \in S)(\forall y \in O' - \{o\})[A'[x, y] = A[x, y]]$
 - $(\forall x \in S - \{s})(\forall y \in O')[A'[x, y] = A[x, y]]$

destroy subject

- Precondition: $s \in S$
- Primitive command: **destroy subject s**
- Postconditions:
 - $S' = S - \{s\}, O' = O - \{s\}$
 - $(\forall y \in O')[A'[s, y] = \emptyset], (\forall x \in S')[A'[x, s] = \emptyset]$
 - $(\forall x \in S')(\forall y \in O')[A'[x, y] = A[x, y]]$

destroy object

- Precondition: $o \in O$
- Primitive command: **destroy object s**
- Postconditions:
 - $S' = S, O' = O - \{o\}$
 - $(\forall x \in S')[A'[x, o] = \emptyset]$
 - $(\forall x \in S)(\forall y \in O)[A'[x, y] = A[x, y]]$

Example: Creating File

Process p creates file f with r and w permissions

```

command make·file( $p, f$ )
  create object  $f$ ;
  enter own into  $a[p, f]$ ;
  enter  $r$  into  $a[p, f]$ ;
  enter  $w$  into  $a[p, f]$ ;
end
  
```

Mono-Operational Commands

- Make process p the owner of file f

```
command make .owner( $p$ ,  $f$ )
    enter own into  $a[p, f]$ ;
end
```

- Single primitive operation in this command
 - So it's *mono-operational*

Conditional Commands

- If p owns f , let p give q r rights over f

```

command grant-rights( $p$ ,  $f$ )
  if own in  $A[p, f]$ 
  then
    enter  $r$  into  $A[q, f]$ ;
  end
  
```

- Single condition in this command
 - So it's *mono-conditional*

Multiple Conditions

- If p has both r and c rights over f , let p give q r and w rights over f

```

command grant · read · file · ifrandc( $p, f$ )
    if  $r$  in  $A[p, f]$  and  $c$  in  $[p, q]$ 
    then
        enter  $r$  into  $A[q, f]$ ;
        enter  $w$  into  $A[q, f]$ ;
    end

```

- Two conditions in this command
 - So it's *bi-conditional*

“Or” Conditions

- If p has either r or c rights over f , let p give q r and w rights over f
 - No “or” operator, so we write command for each possibility
 - Then execute them sequentially
 - Note: if multiple conditions hold, actions may be taken more than once (usually to no effect)

r, c Commands

```

command grant · read · file · ifr(p, f)
  if r in  $A[p, f]$ 
  then
    enter r into  $A[q, f]$ ;
    enter w into  $A[q, f]$ ;
  end
command grant · read · file · ifc(p, f)
  if c in  $A[p, f]$ 
  then
    enter r into  $A[q, f]$ ;
    enter w into  $A[q, f]$ ;
  end

```

r or *c* Command

```

command grant · read · file · ifrorc(p, f)
    grant · read · file · ifr(p, f)
    grant · read · file · ifc(p, f)
end
    
```

Copy

- Allows possessor to give rights to another
- Often attached to a right, so only applies to that right
 - r is read right that cannot be copied
 - rc or $r:c$ is read right that can be copied
 - In this case, called a *copy flag*
- Is copy flag copied with copying the associated right?
 - Depends on rules of model, or instantiation of model

Own

- Usually allows possessor to change entries in ACM column
 - Owner of object can add, delete rights over that object for others
- What can be done is system (instantiation) dependent
 - Some disallow giving rights to specific (set of) users
 - Some disallow passing of copy flag to specific (set of) users

Principle of Attenuation of Privilege

- You increase your rights
- You cannot give rights that you do not possess
 - Restricts addition of rights within a system
- Usually *ignored* for owner
 - Why? Owner gives herself rights; gives them to others; deletes her rights

Now What?

- Very simple model, but very powerful
- Will use this to examine decidability of security
- Will use very simple definition of “secure”:
 - Adding a generic right r where there was not one is *leaking*
 - If a system S begins in initial state s_0 and it cannot leak right r , we consider it secure with respect to the right r

We will formalize this and study it

What is “Secure”?

Leaking

Adding a generic right r where there was not one is *leaking*

Safe

If a system S , beginning in initial state s_0 , cannot leak right r , it is *safe* with respect to the right r .

Here, “safe” = “secure” for an abstract model

What is Does “Decidable” Mean?

Safety Question

Does there exist an algorithm for determining whether a protection system S with initial state s_0 is safe with respect to a generic right r ?

Mono-Operational Commands

Answer:

Yes!

Proof sketch:

Consider minimal sequence of commands c_1, \dots, c_k to leak the right

- Can omit **delete**, **destroy**
- Can merge all **creates** into one

Worst case: insert every right into every entry; with s subjects, o objects, and n rights initially, upper bound is $k \leq n(s + 1)(o + 1)$

Proof (1)

- Consider minimal sequences of commands (of length m) needed to leak r from system with initial state s_0
 - Identify each command by the type of primitive operation it invokes
- Cannot test for *absence* of rights, so **delete**, **destroy** not relevant
 - Ignore them
- Reorder sequences of commands so all **creates** come first
 - Can be done because **enters** require subject, object to exist
- Commands after these **creates** check only for *existence* of right

Proof (2)

- It can be shown (see homework):
 - Suppose s_1, s_2 are created, and commands test rights in $A[s_1, o_1], A[s_2, o_2]$
 - Doing the same tests on $A[s_1, o_1]$ and $A[s_1, o_2] = A[s_1, o_2] \cup A[s_2, o_2]$ gives same result
 - Thus all **creates** unnecessary
 - Unless s_0 is empty; then you need to create it (1 **create**)
- In s_0 :
 - $|S_0|$ number of subjects, $|O_0|$ number of objects, n number of (generic) rights
- In worst case, 1 create
 - So a total of at most $(|S_0| + 1)(|O_0| + 1)$ elements
- So $m \leq n(|S_0| + 1)(|O_0| + 1)$

General Case

Answer:

No

Proof sketch:

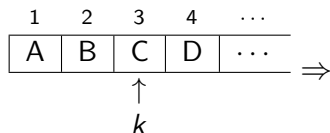
- 1 Show arbitrary Turing machine can be reduced to safety problem
- 2 Then deciding safety problem means deciding the halting problem

Turing Machine Review

- Infinite tape in one direction
- States K , symbols M , distinguished blank \emptyset
- State transition function $\delta(k, m) = (k', m', L)$
 in state k with symbol m under the TM head
 replace m with m' , move head left one square, enter state k'
- Halting state is q_f

Mapping

Turing machine



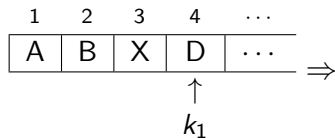
access control matrix representation

	s_1	s_2	s_3	s_4	...
s_1	A	<i>o</i>			...
s_2		B	<i>o</i>		...
s_3			C k	<i>o</i>	...
s_4				D <i>e</i>	...
⋮	⋮	⋮	⋮	⋮	⋮

Turing machine with head over square 3 on tape, in state k and its representation as an access control matrix
o is *own* right
e is *end* right

Mapping

Turing machine



access control matrix representation

	s_1	s_2	s_3	s_4	...
s_1	A	o			...
s_2		B	o		...
s_3			X	o	...
s_4				D k_1 e	...
\vdots	\vdots	\vdots	\vdots	\vdots	\ddots

After $\delta(k, C) = (k_1, X, R)$, where k is the previous state and k_1 the current state

Command Mapping

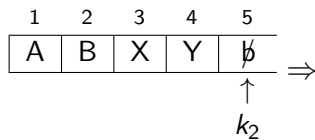
$\delta(k, C) = (k_1, X, R)$ at intermediate becomes:

```

command  $c_{k,C}(s_i, s_{i+1})$ 
if  $o$  in  $A[s_i, s_{i+1}]$  and  $k$  in  $A[s_i, s_i]$  and  $C$  in  $A[s_i, s_i]$ 
then
  delete  $k$  from  $A[s_i, s_i]$ ;
  delete  $C$  from  $A[s_i, s_i]$ ;
  enter  $X$  into  $A[s_i, s_i]$ ;
  enter  $k_1$  into  $A[s_{i+1}, s_{i+1}]$ ;
end
  
```

Mapping

Turing machine



access control matrix representation

	s_1	s_2	s_3	s_4	s_5
s_1	A	o			
s_2		B	o		
s_3			X	o	
s_4				Y	o
s_5					$k_2 e$

After $\delta(k_1, D) = (k_2, Y, R)$, where k_1 is the previous state and k_2 the current state